Of (hyper)graphs and functions of binary variables: Old and recent results

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Outline

- Joint work with Frédéric
- 2 Nonlinear 0-1 optimization
- 3 Standard linearization
- 4 Quadratization

5 Conclusions

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 - QuadratizationUpper boundsLower bounds

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Joint work with Frédéric

At Rutgers University

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- Frédéric's PhD degree: 1989

At Rutgers University



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- Frédéric's PhD degree: 1989
- Advisor: Peter L. Hammer
- Interest in combinatorial structures and functions of 0-1 variables:

P.L. Hammer, F. Maffray. Completely separable graphs. *Discrete Applied Mathematics* 27 (1990), 85-99.

P.L. Hammer, F. Maffray, M. Queyranne. Cut-threshold graphs. *Discrete Applied Mathematics* 30 (1991), 163-179.

C. Benzaken, Y. Crama, P. Duchet, P.L. Hammer, F. Maffray. More characterizations of triangulated and cotriangulated graphs. *Journal of Graph Theory* 14 (1990), 413-422.

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- What does this polynomial look like??

Some examples:

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- If $G = C_4$, then $\alpha_G = \theta_G = x_1 + x_2 + x_3 + x_4 x_1x_2 x_2x_3 x_3x_4 x_1x_4 + x_1x_2x_3 + x_1x_2x_4 + x_1x_3x_4 + x_2x_3x_4 2x_1x_2x_3x_4$

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Theorem (BCDHM 1990)

The polynomial expression of the stability function of G has all its coefficients equal to 0, -1, or + 1 if and only if G is triangulated. Moreover, when this is the case, the coefficients alternate in sign between odd and even degree terms.

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- Generalization: the hypergraph $H = \{123, 124, 34\}$ has $\alpha_H = x_1 + x_2 + x_3 + x_4 - x_3x_4 - x_1x_2x_3 - x_1x_2x_4 + x_1x_2x_3x_4.$

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- Anything special about it? What hypergraphs have all coefficients equal to 0, -1, or +1?

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Definitions

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Multilinear polynomials

Every pseudo-Boolean function can be represented – in a unique way – as a *multilinear polynomial* in its variables, of the form

$$f(x_1,\ldots,x_n)=\sum_{S\in S}a_S\prod_{k\in S}x_k+\sum_{i=1}^na_ix_i$$

where $\mathcal{S} = \{ \mathcal{S} \in 2^{[n]} \mid a_{\mathcal{S}} \neq 0, |\mathcal{S}| \geq 2 \}.$

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Example:

 $f = 4 - 9x_1 - 5x_2 - 2x_3 + 13x_1x_2 + 13x_1x_3 + 6x_2x_3x_4 - 13x_1x_2x_3x_4$

Co-occurrence hypergraph

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$$f(x_1,\ldots,x_n)=\sum_{S\in S}a_S\prod_{k\in S}x_k+\sum_{i=1}^na_ix_i,$$

 $H_f = ([n], S)$ is the *co-occurrence hypergraph* associated with *f*.

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We are frequently interested in:

(MOB)
$$\min_{x \in \{0,1\}^n} \sum_{S \in S} a_S \prod_{k \in S} x_k + \sum_{i=1}^n a_i x_i$$

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 - Direct resolution methods
 - Linearization: extensive literature in integer programming.
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1. Substitute monomials

$$\min \sum_{S \in S} a_S y_S + \sum_{i=1}^n a_i x_i$$

s.t. $y_S = \prod_{k \in S} x_k$, $\forall S \in S$
 $y_S \in \{0, 1\}, \quad \forall S \in S$
 $x_k \in \{0, 1\}$ $\forall k = 1, \dots, n$

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$\min\sum_{S\in\mathcal{S}}a_Sy_S+\sum_{i=1}^na_ix_i$
$\in \mathcal{S}$ s.t. $y_{\mathcal{S}} \leq x_k$, $\forall k \in \mathcal{S}, \forall \mathcal{S} \in \mathcal{S}$
$y_{\mathcal{S}} \geq \sum_{k \in \mathcal{S}} x_k - (\mathcal{S} - 1), \ \forall \mathcal{S} \in \mathcal{S}$
$\in \mathcal{S}$ $y_{\mathcal{S}} \in \{0,1\},$ $\forall \mathcal{S} \in \mathcal{S}$
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3. Linear relaxation

	$\min \sum_{\mathcal{S} \in \mathcal{S}} a_{\mathcal{S}} y_{\mathcal{S}} + \sum_{i=1}^{r}$	$\int_{1}^{1} a_i x_i$
$orall oldsymbol{\mathcal{S}} \in \mathcal{S}$	s.t. $y_S \leq x_k$,	$orall m{k} \in m{S}, orall m{S} \in m{S}$
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Linear relaxation

A natural question: does the standard linearization polytope

$$\boldsymbol{P}_{SL} = \{(\boldsymbol{x}, \boldsymbol{y}) \in [0, 1]^{n+|\mathcal{S}|} \mid \boldsymbol{y}_{S} \leq \boldsymbol{x}_{k} \; \; \forall k \in \boldsymbol{S}, \boldsymbol{y}_{S} \geq \sum_{k \in \boldsymbol{S}} \boldsymbol{x}_{k} - (|\boldsymbol{S}| - 1) \; \; \forall \boldsymbol{S} \in \boldsymbol{\mathcal{S}} \}$$

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- For two or more nonlinear terms, Yes! P_{SL} is in general very weak!!!
- So, when is *P*_{SL} integral?

Co-occurrence hypergraph

Recall: co-occurrence hypergraph

When

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Definition: Berge cycles

For a hypergraph H = (V, S), a **Berge cycle** of length *p* is a sequence

$$(i_1, S_1, i_2, S_2, \ldots, i_p, S_p, i_1),$$

where

*i*₁, *i*₂,..., *i*_p are pairwise distinct vertices of *V*, *S*₁, *S*₂,..., *S*_p are pairwise distinct edges of *S*, *i*_i, *i*_{i+1} ∈ *S*_i for *i* = 1,..., *p* − 1, and *i*₁, *i*_p ∈ *S*_p.

Perfect standard linearization

(E. Rodríguez-Heck, Ch. Buchheim, Y. Crama, 2016)

 P_{SL} is integral if and only if H_f has no Berge cycles.

Proof:

- \leftarrow If H_f is Berge-acyclic then the constraint matrix of P_{SL} is balanced, a property that guarantees integrality.
- ⇒ If H_f has a cycle, then construct an objective function that reaches its optimum at a fractional vertex of P_{SL} .

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- Generalizes a result of Padberg (1989) for quadratic functions.
- Closely related to a result of Crama (1988,1993) for an "irredundant" relaxation of P_{SL}.
- Independently obtained by Del Pia and Khajavirad (2016).

Multilinear optimization in binary variables

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 - Yes, in many ways!

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- Conversely...

Quadratization

The quadratic function g(x, y), $(x, y) \in \{0, 1\}^{n+m}$ is an *m*-quadratization of the pseudo-Boolean function f(x), $x \in \{0, 1\}^n$, if

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The y-variables are called *auxiliary* variables.

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• min{ $f(x) | x \in \{0,1\}^n$ } = min{ $g(x,y) | (x,y) \in \{0,1\}^{n+m}$ }.

Does every function f have a quadratization?

Existence

Existence of quadratizations (Rosenberg 1975)

Given the multilinear expression of a pseudo-Boolean function $f(x), x \in \{0, 1\}^n$, one can find in polynomial time a quadratization g(x, y) of f(x).

- Idea: in each term ∏_{i∈A} x_i of f, with {1,2} ⊆ A, replace the product x₁x₂ by a new variable y;
- Introduce a penalty term to force y = x₁x₂ in every minimizer of the transformed expression;

•
$$t(x,y) = \left(\prod_{i \in A \setminus \{1,2\}} x_i\right) y + M(x_1x_2 - 2x_1y - 2x_2y + 3y).$$

• Potential drawbacks: introduces many auxiliary variables, big *M*.

Questions arising...

- Many quadratization procedures proposed in recent years. Which ones are "best"? Small number of variables, of positive terms, good properties with respect to persistencies, submodularity?
- Easier question: What if f is a single monomial?
- How many variables are needed in a quadratization?

• etc.

Refs: Boros and Gruber (2011); Buchheim and Rinaldi (2007); Fix, Gruber, Boros and Zabih (2011): Freedman and Drineas (2005); Ishikawa (2011); Kolmogorov and Zabih (2004); Ramalingam et al. (2011); Rosenberg (1975); Rother et al. (2009); Živný, Cohen and Jeavons (2009); etc.

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Upper bounds

Outline

- Joint work with Frédéric
- 2 Nonlinear 0-1 optimization
 - Standard linearization
- Quadratization
 Upper bounds
 Lower bounds

Conclusions

• How many auxiliary variables are needed in general?

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Best known bound, until recently.

Upper bound

• Upper bound based on termwise quadratizations:

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For every *n*-variable pBf, one can find in polynomial time a quadratization involving at most $\lfloor \frac{n-1}{2} \rfloor 2^n$ auxiliary variables.

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• We prove:

Theorem: upper bound (Math. Prog. (2017))

For every *n*-variable pBf, one can find in polynomial time a quadratization involving at most $O(2^{n/2})$ auxiliary variables.

Pairwise cover

Based on a construction using small pairwise covers:

Pairwise cover

A hypergraph \mathcal{H} is a *pairwise cover* of $\{1, \ldots, n\}$ if, for every $S \subseteq \{1, \ldots, n\}$ with $|S| \ge 3$, there are sets $A, B \in \mathcal{H}$ such that |A| < |S|, |B| < |S| and $A \cup B = S$.

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- Idea of the proof: write $\prod_{i \in S} x_i = (\prod_{j \in A} x_j)(\prod_{k \in B} x_k)$; substitute y_A for $\prod_{j \in A} x_j$ and y_B for $\prod_{k \in B} x_k$;
- Introduce a penalty term to force the correct values of y_A and y_B in every minimizer of the transformed expression.

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- $\mathcal{P}(even) = all subsets of even integers in \{1, ..., n\}.$
- $\mathcal{P}(odd) = all subsets of odd integers in \{1, \ldots, n\}.$
- $\mathcal{H} = \mathcal{P}(even) \cup \mathcal{P}(odd)$ is a "small" pairwise cover with size $O(2^{n/2})$.

Outline

- Joint work with Frédéric
- 2 Nonlinear 0-1 optimization
 - B) Standard linearization



5 Conclusions

Lower bound

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There are pseudo-Boolean functions of *n* variables for which every quadratization must involve at least $\Omega(2^{n/2})$ auxiliary variables.

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Theorem: lower bound (Math. Prog. (2017))

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- This lower bound matches the $O(2^{n/2})$ upper bound.
- Non constructive proof based on dimensionality argument: if too few auxiliary variables, then we cannot generate the whole vector space of pseudo-Boolean functions.

Outline

- Joint work with Frédéric
- 2 Nonlinear 0-1 optimization
- 3 Standard linearization
 - Quadratization
 Upper bounds
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- See also

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Yves CRAMA and Peter L. HAMMER Cambridge University Press, 2011 710 pages

with contributions by C. Benzaken, E. Boros, N. Brauner, M.C. Golumbic, V. Gurvich, L. Hellerstein, T. Ibaraki, A. Kogan, K. Makino, B. Simeone

