

Fractional chromatic number and girth

François Pirot, joint work with J.S. Sereni

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Stable sets

A *stable set* of a graph is a subset of its vertices with no edges in between. It can be:

- *maximal*: Any other vertex of the graph shares an edge with at least one of its vertices.
- *maximum*: Its size is the biggest possible in the graph.

Colouring and Stable Sets

Stable sets

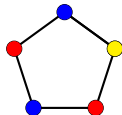
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Chromatic Number

- A *k-colouring* of some graph $G = (V, E)$ is a function $c : V \rightarrow [k]$ such that $uv \in E \Rightarrow c(u) \neq c(v)$. In other words, this is a partition of V of size k into stable sets. The *chromatic number* $\chi(G)$ of G is the minimum k such that there is a k -colouring of G .

A colouring of C_5 needs 3 colours : $\chi(C_5) = 3$



The chromatic number formulated as a Linear Program

The Linear Program

Let G be some graph, and \mathcal{S} be the set of (maximal) stable sets of G .

$$\begin{aligned} \chi(G) = & \min \sum_{S \in \mathcal{S}} w_S \\ \text{such that} & \begin{cases} \forall v \in V(G), & \sum_{S \ni v} w_S \geq 1 \\ \forall S \in \mathcal{S}, & w_S \in \{0, 1\} \end{cases} \end{aligned}$$

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Fractional Chromatic Number

The *fractional chromatic number* $\chi_f(G)$ of some graph G is the solution to the fractional relaxation of the linear program computing $\chi(G)$.

It can also be defined through *fractional colourings*.

- A (a, b) -colouring of some graph $G = (V, E)$ is a function $c : V \rightarrow \binom{[a]}{b}$ such that $uv \in E \Rightarrow c(u) \cap c(v) = \emptyset$.
- $\chi_f(G) = \inf \left\{ \frac{a}{b} \mid G \text{ has a } (a, b)\text{-colouring} \right\}$

Illustration and Properties

Remark

A (a, b) -colouring of some graph G can be seen as a a -colouring of $G \boxtimes K_b$.

A $(5, 2)$ -colouring of C_5 (every maximal stable set gets weight $\frac{1}{2}$)
 $\chi_f(C_5) = 2.5$

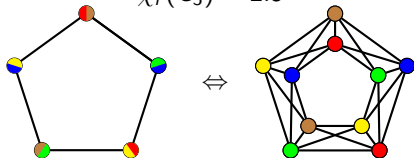
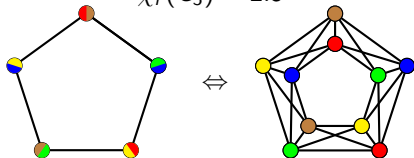


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Properties

For any graph G on n vertices, of maximum degree Δ , clique and stability numbers ω and α (size of the biggest clique / stable set):

$$\omega \leq \chi_f(G) \leq \chi(G) \leq \Delta + 1$$

$$\frac{n}{\alpha} \leq \chi_f(G)$$

Theorem (Molloy, 2017)

If a graph G of maximum degree Δ is triangle-free (so of girth at least 4), then:

$$\chi(G) \leq (1 + o(1)) \frac{\Delta}{\ln \Delta}.$$

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For any graph G of maximum degree Δ and of clique number ω ,

$$\chi_f(G) \leq \frac{\omega + \Delta + 1}{2}.$$

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Comment on these theorems

The second theorem gives a bound for triangle-free graph: $\chi_f \leq \frac{\Delta+3}{2}$. This is a lot weaker than the bound given by the first theorem in the asymptotic, but for small degrees ($\Delta \geq 4$) there is no better known bound!

The greedy fractional colouring algorithm

For some graph G , fix a probability distribution on the stable sets of any induced subgraph of G . We denote by \mathbf{S} the corresponding random stable set.

The algorithm

- 1 Set $G_0 = G$.
- 2 At each step i , give to every stable set I of G_i a weight proportional to $\mathbb{P}[\mathbf{S} = I]$ in such a way that the new maximum induced weight on the vertices of G_i is exactly 1. (We take care never to exceed 1)
- 3 Define G_{i+1} as the graph G_i where those new vertices with weight 1 are removed. Stop if this is the empty graph.

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Lemma (weak version)

If for every induced subgraph H of G , every random stable set \mathbf{S} of H , and every vertex $v \in V(H)$,

$$\alpha \mathbb{P}[v \in \mathbf{S}] + \beta \mathbb{E}[|N(v) \cap \mathbf{S}|] \geq 1,$$

then the returned fractional colouring is of weight at most

$$\alpha + \beta \Delta(G).$$

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Lemma (P, Sereni [2018+])

Fix some depth $r \geq 1$. If for every induced subgraph H of G , every random stable set \mathbf{S} of H , and every vertex $v \in V(H)$,

$$\sum_{i=0}^r \alpha_i(v) \mathbb{E}[|N^i(v) \cap \mathbf{S}|] \geq 1,$$

then the returned fractional colouring is of weight at most

$$\max_{v \in V(G)} \sum_{i=1}^r \alpha_i(v) |N^i(v)|.$$

Proof of the fractional Reed's bound

- Let v be some vertex in G , and \mathbf{S} a random maximum stable set of G . We show that

$$\frac{\omega(G) + 1}{2} \mathbb{P}[v \in \mathbf{S}] + \frac{1}{2} \mathbb{E}[|N(v) \cap \mathbf{S}|] \geq 1$$

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 - Event X_1 : The uncovered part of $N(v)$ is a clique (of size $k \in [1, \omega]$). Then the events $u \in \mathbf{S}$ for $u \in N[v] \setminus N(\mathbf{R})$ are equally likely.

$$\mathbb{P}[v \in \mathbf{S} \mid X_1] = \frac{1}{k}, \quad \mathbb{E}[|N(v) \cap \mathbf{S}| \mid X_1] = \frac{k-1}{k}$$

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- Event X_2 : At least 2 independent neighbours of v are not covered by \mathbf{R} . Then $|N(v) \cap \mathbf{R}| \geq 2$, and $v \notin \mathbf{R}$.

$$\mathbb{P}[v \in \mathbf{S} \mid X_2] = 0, \quad \mathbb{E}[|N(v) \cap \mathbf{S}| \mid X_2] \geq 2$$

Limitation

When using the uniform distribution on maximum stable sets, the algorithms cannot beat Reed's bound for some bipartite graphs. These are highly irregular; considering regular graphs helps avoiding this, at the cost of proving bounds only on n/α instead of χ_f .

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Independence ratio upper bounds (P, Sereni [2018+])

We propose some upper bounds for $\frac{n}{\alpha}$ for graphs G on n vertices and stability number α , depending on its girth and (small) maximum degree.

girth	4	5	6	8	10	12
$\Delta = 3$	2.8	2.8	≈ 2.7272	≈ 2.6252	≈ 2.5571	≈ 2.5103
$\Delta = 4$	3.375	3.28	≈ 3.1538	≈ 3.0385	?	?

New results

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Corollary

These are upper bounds for χ_f in the class of vertex transitive graphs.

Less constrained lemma (P, Sereni [2018+])

Fix some depth $r \geq 1$, and let S be a random stable set of some d -regular graph G , such that for every vertex $v \in V(G)$,

$$\sum_{i=0}^r \alpha_i \mathbb{E} [|X_i(v) \cap S|] \geq 1,$$

where $X_i(v)$ is the random variable counting the number of paths of length i beginning in v and ending in S . Then

$$\frac{n}{\alpha(G)} \leq \alpha_0 + \sum_{i=1}^r \alpha_i d(d-1)^{i-1}.$$

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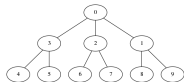
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Method overview

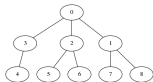
- Enumerate all the possible partially covered neighbourhoods up to depth r of G , and compute $(\mathbb{E}_{X_0}, \dots, \mathbb{E}_{X_r})$ for each of them.
- Compute the best possible $(\alpha_0, \dots, \alpha_r)$ through a linear program.

Computer work

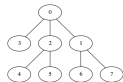
The 10 possible partially covered neighbourhoods of depth 2 for 3-regular graphs of girth 6, with the corresponding value for $(\mathbb{E}_{X_0}, \mathbb{E}_{X_1}, \mathbb{E}_{X_2})$.



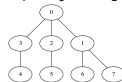
$$(1, 0, 6)$$



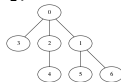
$$(1, 0, 5)$$



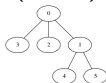
$$\left(\frac{1}{2}, \frac{1}{2}, 4\right)$$



$$(1, 0, 4)$$



$$\left(\frac{1}{3}, 1, \frac{8}{3}\right)$$



$$(0, 2, 2)$$



$$(1, 0, 3)$$



$$\left(\frac{1}{5}, \frac{8}{5}, \frac{6}{5}\right)$$



$$\left(0, \frac{5}{2}, \frac{1}{2}\right)$$



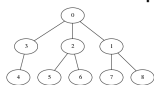
$$(0, 3, 0)$$

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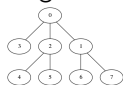
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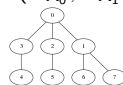
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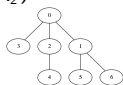
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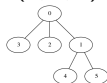
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$$\left(\frac{1}{5}, \frac{8}{5}, \frac{6}{5}\right)$$



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$$(0, 3, 0)$$

Linear Program computing the desired bound for d -regular graphs

$$\text{minimize} \quad \alpha_0 + \sum_{i=1}^r d(d-1)^{i-1} \alpha_i$$

$$\text{such that} \quad \begin{cases} \forall v, \forall R, & \sum_{i=0}^r \alpha_i \mathbb{E}[X_i(v) \mid S \setminus N^r[v] = R] \geq 1 \\ \forall i, & \alpha_i \geq 0 \end{cases}$$

A better than Reed's upper bound for graphs of girth 7

Theorem (P, Sereni [2018+])

For any graph G of maximum degree Δ and girth at least 7:

$$\chi_f(G) \leq \frac{2\Delta + 9}{5}$$

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Comment

This result was obtained with neighbourhoods at depth $r = 2$. Surprisingly, increasing the depth does not give any better bound for cubic graphs, even though we know that the real bound is 2.8 and not the value 3 given by the theorem.

This is enough to believe that the value 3.4 given by the theorem for graphs of maximum degree 4 and girth 7 is far from the optimal.

Hard-core distribution on maximal stable sets

We use a *hard-core* random distribution on *maximal* stable sets instead of the *uniform* distribution on *maximum* stable sets.

Let \mathbf{S} be the corresponding random stable set, and \mathcal{S} be the set of maximal stable sets of G , then

$$\forall I \in \mathcal{S}, \mathbb{P}_\lambda[\mathbf{S} = I] = \frac{\lambda^{|I|}}{\sum_{J \in \mathcal{S}} \lambda^{|J|}}, \text{ for any } \lambda > 0.$$

Presentation of the tools needed for the proof

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Main difficulty

For some neighbourhood $W = N^r[v]$, let $\mathbf{R} := \mathbf{S} \setminus W$. It must hold that the vertices of \overline{W} not covered by \mathbf{R} must be covered by $\mathbf{S} \cap W$.

We consider neighbourhoods at distance $r = 2$, and ask for girth 7 in order to ensure that the vertices in \overline{W} can be covered by at most one vertex in W .

- We can imagine replacing the girth constraint by any other local constraint which is well expressed when we enumerate neighbourhoods at depth r : for instance bounding the number of triangles in which every vertex appears, or forbidding any fixed small enough subgraph.

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Thank you for your attention!